WEST Search History

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DATE: Tuesday, September 25, 2007

Hide?	<u>Set</u> Name	Query	<u>Hit</u> Count
	DB =	PGPB, USPT, EPAB, JPAB, DWPI, TDBD; PLUR=YES; OP=ADJ	
	L32	position and orientation and L31	. 33
	L31	(13 or 14) and L30	69
	L30	landed and landing and foot and robot\$6	133
	L29	landed and landing and foot and footstep and robot\$6	5
	L28	landed and landing and foot and footstep and (L3 or L4)	2
	L27	landded and landing and foot and footstep and (L3 or L4)	0
	L26	landded and landing and foot and footstep and L17	0
	L25	landded and landing and foot and L24	0
	L24	posture and L23	33
	L23	gravity and coordinate and L22	34
	L22	estimat\$3 and position and L21	40
	L21	dynamics same model and L18	52
	L20	dyanamics and L18	0
	L19	dyanamics same model and L18	0
	L18	L16 and L17	143
	L17	movement or trajectory and L16	2480777
	L16	floor and zmp and L3	152
	L15	floor and zmp and L14	0
	L14	(5024920 5173382 5490103 5557564 5901829 6201488 6521838 6518503 6695663 6592418 5733819 6027554 6663326 6694847 6685863 4252414 4588518 4561746 4719331 5118090 5434926 5419740 5558196 5527940 5716481).pn.	47
	L13	motion pattern and L11	2
□ .		motion pattern and stor\$3 and L11	0

L11	freedom and L10	5
L10	L8 and L9	6
L9	L8 and gait or gate	1133571
L8	('6580969' '6493606' '6463356' '6289265' '6243623' '5872893' '5841258' '5838130' '5594644' 'EP 1136193A' 'EP 1103451A')!.ABPN1,NRPN,PN,TBAN,WKU.	18
L7	('20030019671' '20020138359' '6591923' '6458011')!.ABPN1,NRPN,PN,TBAN,WKU.	7
L6	(legged robot or pet robot or humanoid near10 robot) motion and pattern	13
L5	(legged robot or pet robot or humanoid near10 robot) motion and pattern and L4	0
L4	6059092 6059092 6068201 6456728 6505098 6711469 5402050 5525883 5841258 6463356 4614504 5040626 5343397 5369346 5378969 5644204 5672924 5838130 5872893 6229552).pn.	97
L3	(700/245 700/246 700/251 700/253 700/260 700/261 or 318/568.1 318/568.12 318/568.16 318/568.17 318/568.2 or 901/1 901/9 901/46 or 180/8.1 180/8.6 180/65.1 or 701/23 or 320/116 320/120 or 446/376 446/384).ccls.	9510
L2	6580969.pn.	2

END OF SEARCH HISTORY

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